

Convective Instability In Ferromagnetic Fluids With Cubic Temperature Profiles

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ABSTRACT

The thermoconvective instability on the onset of convection in ferrofluids in presence of cubic temperature profiles is studied with consistent magnetic field applied vertically. The lower boundary and upper boundary are considered to be rigid-isothermal and ferromagnetic. The Galerkin technique, a numerical method with Chebyshev second kind polynomials is used as test functions to extract the critical stability parameters. The results found that the stability of convection in ferromagnetic fluids is considerably affected by cubic temperature profiles and the mechanism for suppressing or augmenting the same is discussed in detail. It is noticed that the effect of M_3 nonlinearity of the fluid magnetization is to hasten, but increase in Bi the heat transfer coefficient is to setback the onset of ferroconvection. Further, increase in Bi is to lessen the size of convection cells.

Keywords: cubic temperature profiles, ferroconvection, Galerkin technique.

I. INTRODUCTION

Ferromagnetic fluids are stable colloidal suspensions of magnetic nano-particles detached in a carrier liquid. There are two special features in ferrofluids which are not found in ordinary fluids, the Kelvin force and the body couple (see Rosensweig [1]). There have been several studies on thermal convection in a ferrofluid layer called ferroconvection. The theory of thermoconvective instability in a ferrofluid layer began with Finlayson [2] and extensively continued over the years (Stiles and Kagan [3], Shliomis and Smorodin [4], Ganguly et al. [5], Kaloni and Lou [6], Nanjundappa et al. [7], Sunil and Amit Mahajan [8], Shivakumara et al. [9]). In the past two decades several investigations were done to understand the control of convection in ferrofluids. Nanjundappa et al. [10] have investigated the effect of the penetrative Bénard-Marangoni ferroconvection in a ferromagnetic fluid layer. Nanjundappa et al. [11] did widespread work on the Bénard-Marangoni ferroconvection with internal heat source in the presence of vertically applied consistent magnetic field. The same authors [12] have studied effect of the temperature dependent viscosity on the Onset of Marangoni-Bénard ferroconvection. Recently, Arunkumar and Nanjundappa [13] have explained the effect of MFD on Bénard-Marangoni ferroconvection in a rotating ferrofluid layer. However, the effects of basic temperature profiles also have considerable attention in the literature. Idris and Hashim [14] conducted theoretical investigation of linear feedback control on Bénard-Marangoni under the influence of cubic temperature profiles. Nanjundappa et al. [15] and Nanjundappa and Arunkumar [16] respectively investigated the effect of cubic profiles on Bénard-Marangoni convection with MFD viscosity and the effect of the same profiles in Brinkman porous medium. The intent of the current analysis is to understand the stability of thermomagnetic convection in ferrofluids with cubic temperature profiles. The study helps in understanding control of convection which is useful in many heat transfer related problems particularly in materials science processing.

II. MATHEMATICAL FORMULATION

The physical constitution of the problem is as shown in Fig 1. A Cartesian system (x, y, z) is used with the origin at the bottom and z -axis is directed vertically upward. Gravity acts in the negative z -direction, $\vec{g} = -g\hat{k}$, and a uniform magnetic field H_0 acting normal to the boundaries.

We assume that the fluid is incompressible and the governing equations are,

$$\rho = \rho_0[1 - \alpha_t(T - T_0)] \quad (1)$$

At the boundary $z = 0$ a stable heat flux condition of the form

$$-k_t \frac{\partial T}{\partial z} = q_0 \quad (2)$$

is used, while at the boundary $z = d$ a general thermal boundary condition of the form

$$-k_t \frac{\partial T}{\partial z} = h_t(T - T_\infty) \quad (3)$$

is invoked.

$$\nabla \cdot \vec{q} = 0 \quad (4)$$

$$\rho_0 \left[\frac{\partial \vec{q}}{\partial t} + (\vec{q} \cdot \nabla) \vec{q} \right] = -\nabla p + \rho \vec{g} + \mu_0 (\vec{M} \cdot \nabla) \vec{H} + \mu (\nabla^2 \vec{q}) \quad (5)$$

$$\left[\rho_0 C_{V,H} - \mu_0 \vec{H} \cdot \left(\frac{\partial \vec{M}}{\partial T} \right)_{V,H} \right] \frac{DT}{Dt} + \mu_0 T \left(\frac{\partial \vec{M}}{\partial T} \right)_{V,H} \cdot \frac{D\vec{H}}{Dt} = k_t \nabla^2 T \quad (6)$$

$$\nabla \cdot \vec{B} = 0, \nabla \times \vec{H} = 0 \text{ or } \vec{H} = \nabla \phi \quad (7a, b)$$

$$\vec{B} = \mu_0 (\vec{M} + \vec{H}) \quad (8)$$

$$\vec{M} = \frac{\vec{H}}{H} M(H, T) \quad (9)$$

$$M = M_0 + \chi(H - H_0) - K(T - T_0) \quad (10)$$

where, p the pressure, q the velocity, T the temperature, t the time, \vec{B} the magnetic induction, \vec{H} the intensity of magnetic field. \vec{M} the magnetization, ρ_0 the reference density, α_t the thermal expansion coefficient, μ_0 the magnetic permeability of vacuum, k_t the thermal conductivity, $\bar{T} = (T_0 + T_1)/2$ the average temperature, $\chi = (\partial M / \partial H)_{H_0, T_0}$ the magnetic susceptibility, $K = -(\partial M / \partial T)_{H_0, T_0}$ the pyromagnetic co-efficient, $C_{V,H}$ the specific heat capacity at constant volume and magnetic field per unit mass.

The basic state is assumed to be quiescent and the basic state solution is given by

$$\vec{q}_b = 0, \quad p_b(z) = p_0 - \rho_0 g z - \frac{1}{2} \rho_0 \alpha_t g \beta z^2 - \frac{\mu_0 M_0 K \beta}{1 + \chi} z - \frac{\mu_0 K^2 \beta^2}{2(1 + \chi)^2} z^2, \\ -\frac{dT_b}{dz} = f(z), \quad \vec{H}_b(z) = \left[H_0 - \frac{K \beta z}{1 + \chi} \right] \hat{k}, \quad \vec{M}_b(z) = \left[M_0 + \frac{K \beta z}{1 + \chi} \right] \hat{k}. \quad (11)$$

To study the stability of the system, we perturb all the variables in the form

$$\vec{q} = \vec{q}', \quad p = p_b(z) + p', \quad \rho = \rho_b(z) + \rho', \\ T = T_b(z) + T', \quad \vec{H} = \vec{H}_b(z) + \vec{H}', \quad \vec{M} = \vec{M}_b(z) + \vec{M}' \quad (12)$$

where, \vec{q}' , p' , ρ' , T' , \vec{H}' and \vec{M}' are perturbed variables and are assumed to be small. Substituting Eq. (12) into Eqs. (8) and (9) and using Eq. (7), we obtain

$$\begin{aligned} H_x + M_x &= (1 + M_0 / H_0) H_x \\ H_y + M_y &= (1 + M_0 / H_0) H_y \\ H_z + M_z &= (1 + \chi) H_z - K T \end{aligned} \quad (13)$$

where, (H_x, H_y, H_z) and (M_x, M_y, M_z) are the (x, y, z) components of the magnetic field and magnetization, respectively.

Again substituting Eq. (12) into momentum Eq. (5), linearizing, eliminating the pressure term and using Eq. (13) the z -component of the resulting equation is:

$$\left(\rho_0 \frac{\partial}{\partial t} - \mu \nabla^2 \right) \nabla^2 w = \rho_0 \alpha_t g \nabla_1^2 T - \mu_0 K f(z) \frac{\partial}{\partial z} (\nabla_1^2 \varphi) + \frac{\mu_0 K^2}{1 + \chi} f(z) \nabla_1^2 T \quad (14)$$

where, $\nabla_1^2 = \partial^2 / \partial x^2 + \partial^2 / \partial y^2$ is the horizontal Laplacian operator.

As before, substituting Eq. (12) into energy Eq. (6), linearizing and we obtain

$$(\rho_0 C_0) \frac{\partial T}{\partial t} - \mu_0 K T_0 \frac{\partial}{\partial t} \left(\frac{\partial \varphi}{\partial z} \right) = \left((\rho_0 C_0) - \frac{\mu_0 K^2 T_0}{1 + \chi} \right) w f(z) + k_t \nabla^2 T \quad (15)$$

where, $(\rho_0 C_0) = \rho_0 C_{V,H} + \mu_0 H_0 K$.

Equations (7a, b), after substituting Eq. (12) and using Eq. (13), may be written as

$$\left(1 + \frac{M_0}{H_0} \right) \nabla_1^2 \varphi + (1 + \chi) \frac{\partial^2 \varphi}{\partial z^2} - K \frac{\partial T}{\partial z} = 0. \quad (16)$$

The normal mode analysis of the dependent variables is assumed in the form

$$\{w, T, \varphi\} = \{W, \Theta, \Phi\}(z) e^{i(\ell x + m y)} \quad (17)$$

where, ℓ and m are wave numbers in the x and y directions, respectively.

Substituting Eq. (17) into Eqs. (14) - (16) and non-dimensionalizing the variables by setting

$$(x^*, y^*, z^*) = \left(\frac{x}{d}, \frac{y}{d}, \frac{z}{d} \right), \quad f(z)^* = \frac{1}{\beta} f(z), \quad t^* = \left(\frac{\nu}{d^2} \right) t, \quad w^* = \frac{d}{\nu} w,$$

$$\Theta^* = \frac{\kappa}{\beta \nu d}, \quad \Phi^* = \frac{(1 + \chi) \kappa}{K \beta \nu d^2} \Phi,$$

where, $\nu = \frac{\mu}{\rho_0}$ is the kinematic viscosity, $\kappa = \frac{k_t}{\rho_0 c_0}$ is the thermal diffusivity. we obtain

$$(D^2 - a^2)^2 W = a^2 R_t \Theta - a^2 R_m f(z) [D\Phi - \Theta] \quad (18)$$

$$(D^2 - a^2) \Theta = -(1 - M_2) W f(z) \quad (19)$$

$$(D^2 - a^2 M_3) \Phi - D\Theta = 0. \quad (20)$$

In the above equations, a the overall horizontal wave number, R_t the thermal Rayleigh number, R_m the magnetic Rayleigh number, M_2 the non-dimensional magnetic parameter and neglected in the subsequent analysis because the value is very small(see Finlayson[2]), and $f(z)$ is the non-dimensional temperature gradient such that

$$\int_0^1 f(z) dz = 1.$$

Equations (18) - (20) are solved using the boundary conditions:

$$W = DW = \Theta = \Phi = 0 \text{ at } z = 0 \quad (21a)$$

$$W = DW = D\Theta + Bi \Theta = \Phi = 0 \text{ at } z = 1 \quad (21b)$$

where, $Bi = h_i d / k_i$. The case $Bi = 0$ and $Bi \rightarrow \infty$ respectively correspond to constant heat flux and isothermal conditions at the upper boundary.

Following Dupont et al.[17] and Chiang [18], we consider the steady-state temperature profile as given by:

$$T_b = \bar{T}_{os} - a_1(\bar{z} - d) - a_2(\bar{z} - d)^2 - a_3(\bar{z} - d)^3, \quad (22)$$

In non-dimensional form, the $f(z)$ in Eqs. (18)-(20) is given by:

$$f(z) = a_1^* + 2a_2^* (z - 1) + 3a_3^* (z - 1)^2. \quad (23)$$

The different temperature profiles studied in this paper are listed in Table 1.

III. METHOD OF SOLUTION

Equations (18) - (20) together with the boundary conditions constitute an eigenvalue problem with Rayleigh number R_i as an eigenvalue. The resulting problem is solved by using the Galerkin technique. In this method, the test (weighted) functions are assumed as

$$W = \sum_{i=1}^n A_i W_i(z), \quad \Theta(z) = \sum_{i=1}^n C_i \Theta_i(z), \quad \Phi(z) = \sum_{i=1}^n D_i \Phi_i(z) \quad (24)$$

where, the trial functions $W_i(z)$, $\Theta_i(z)$ and $\Phi_i(z)$ will be generally chosen in such a way that they satisfy the respective boundary conditions, and A_i , C_i and D_i are constants. Substituting Eq.(24) into Eqs.(18) - (20), multiplying the Eq. (18) by $W_j(z)$, Eq. (19) by $\Theta_j(z)$ and Eq. (20) by $\Phi_j(z)$, performing the integration by parts with respect to z between $z = 0$ and $z = 1$ and using the conditions (21a,b), we obtain the system of linear homogeneous algebraic equations:

$$C_{ji}A_i + D_{ji}C_i + E_{ji}D_i = 0 \quad (25)$$

$$F_{ji}A_i + G_{ji}C_i = 0 \quad (26)$$

$$H_{ji}C_i + I_{ji}D_i = 0. \quad (27)$$

The coefficients $C_{ji} - I_{ji}$ are given by

$$C_{ji} = \langle D^2 W_j D^2 W_i \rangle + (2a^2) \langle DW_j DW_i \rangle + a^4 \langle W_j W_i \rangle$$

$$D_{ji} = -a^2 (R_i + f(z) R_m) \langle \Theta_j W_i \rangle$$

$$E_{ji} = a^2 R_m \langle f(z) W_j D \Phi_i \rangle$$

$$F_{ji} = -\langle f(z) \Theta_j W_i \rangle$$

$$G_{ji} = \langle D \Theta_j D \Theta_i \rangle + a^2 \langle \Theta_j \Theta_i \rangle + Bi \Theta_j(1) \Theta_i(1)$$

$$H_{ji} = \langle \Phi_j D \Theta_i \rangle$$

$$I_{ji} = \langle D \Phi_j D \Phi_i \rangle + a^2 M_3 \langle \Phi_j \Phi_i \rangle$$

where, the inner product is defined as $\langle \dots \rangle = \int_0^1 (\dots) dz$.

The above set of homogeneous algebraic equations can have a non-trivial solution if and only if

$$\begin{vmatrix} C_{ji} & D_{ji} & E_{ji} \\ F_{ji} & G_{ji} & 0 \\ 0 & H_{ji} & I_{ji} \end{vmatrix} = 0. \quad (28)$$

The eigenvalue has to be extracted from the characteristic Eq.(28). We select the trial functions as

$$W_i = (z^4 - 2z^3 + z^2)T_{i-1}^*, \quad \Theta_i = z(1 - z/2)T_{i-1}^* \quad \text{and} \quad \Phi_i = (z^2 - z)T_{i-1}^*. \quad (29)$$

where, T_i^* s are the second kind Chebyshev polynomials.

III. RESULTS AND DISCUSSIONS

The resulting eigenvalue problem is numerically solved by Galerkin technique. The outcome presented here are for $i = j = 6$ th order at which the convergence is achieved, in general.

Fig. 2 shows the locus of R_{tc} and R_{mc} for various values of M_3 with three different forms of temperature profiles. In the figure, the regions over and under the curves, correspond respectively to unstable and stable ones. It is observed that there is a strong combination between R_{tc} and R_{mc} that, an increase in the one decreases the other. This shows that, the magnetic forces becomes negligible when the buoyancy forces are predominant and vice-versa. The stability of curves are slightly bowed and in the absence of buoyancy forces ($R_{tc} = 0$), the instability sets in at higher values of R_{mc} indicating the system is more stable when the magnetic forces alone are present. Fig. 2 demonstrated that increasing M_3 has a destabilizing effect on the system. Nevertheless, this destabilization is only marginal. This may be due to the fact that a higher value of M_3 would arise either due to a larger temperature gradient or larger pyromagnetic coefficient. Both these factors are conducive for generating a larger gradient in the Kelvin body force field, possibly promoting the instability. Besides, for a fixed value of M_3 , the R_{tc} for cubic 1 temperature profile with $a_1^* = 0, a_2^* = 0, a_3^* = 1$ is shown to be the most stabilizing of all the considered types of temperature profiles, that is, $(R_{tc})_{linear} < (R_{tc})_{cubic2} < (R_{tc})_{cubic1}$. That is, the system is most unstable (i. e., augments convection) in the case of linear temperature gradient because the jump in temperature occurs nearer the less restrictive free surface, whereas the cubic1 temperature gradient makes the system more stable.

Fig. 3 shows the variations of R_{tc} and R_{mc} for different values of heat transfer coefficient B_i with three different forms of temperature profiles. From the figure it is evident that an increase in the value of heat transfer coefficient B_i is to increase the critical Rayleigh number and hence its effect is to delay the ferroconvection. This may be due to the fact that increasing in B_i , the thermal disturbances can easily dissipate into the ambient surrounding due to a better convective heat transfer coefficient at the top surface and hence higher heating is required to make the system unstable. In the figure, the R_{tc} for cubic 1 temperature profile is shown to be the most stabilizing of all the considered types of temperature profiles, that is, $(R_{tc})_{linear} < (R_{tc})_{cubic2} < (R_{tc})_{cubic1}$. Hence cubic1 temperature gradient makes the system more stable and delays the onset of convection. Further in fig 4 we can observe that increase in B_i increases the critical wave number a_c and hence its effect is to contract the dimension of convection cells.

IV. CONCLUSIONS

The linear stability theory is used to investigate the result of different forms of cubic state temperature profiles on the onset ferroconvection in a ferrofluid layer. The cubic 1 temperature profile increases considerably making the system more stable compared to the other cases and are suitable for laboratory experimentation with a simulated microgravity environment. The result of increase in B_i is to setback the onset of ferroconvection, while increase in M_3 is to advance the onset of ferroconvection.

Table 1: Reference steady-state temperature gradients					
Model	Reference steady-state temperature gradient	$f(z)$	a_1^*	a_2^*	a_3^*
1	Linear	1	1	0	0
2	Cubic 1	$3(z-1)^2$	0	0	1
3	Cubic 2	$0.66 + 1.02(z-1)^2$	0.66	0	0.34

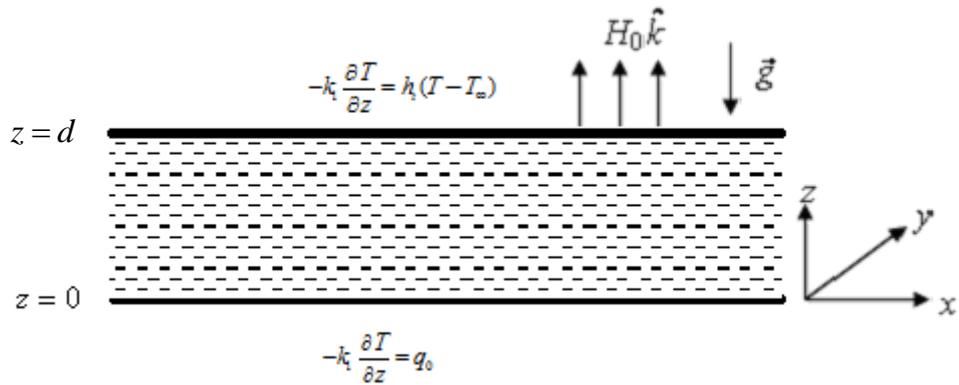


Figure. 1 Physical Configuration

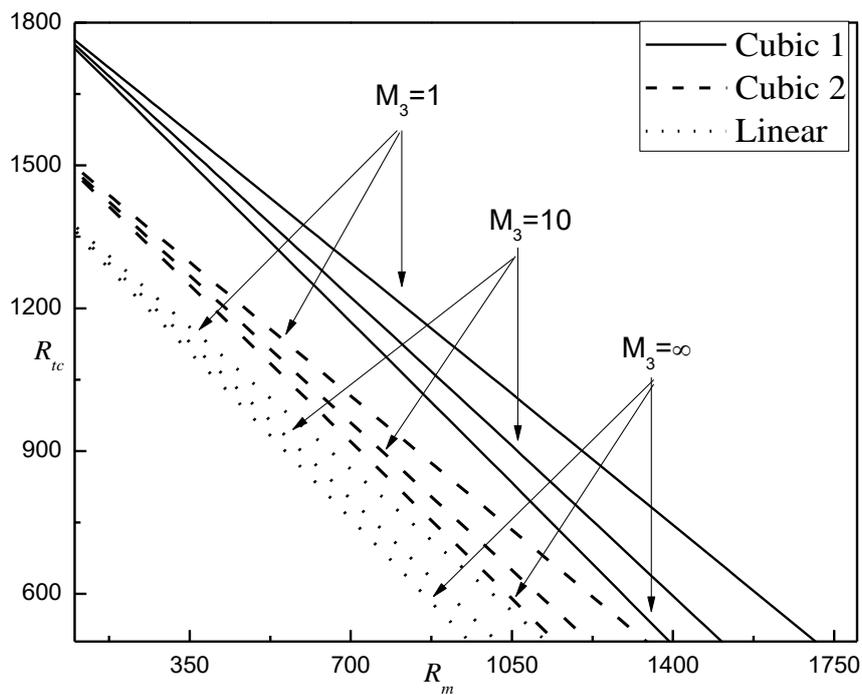


Figure. 2 Locus of R_{tc} vs R_m for different values of M_3 when $B_1=2$.

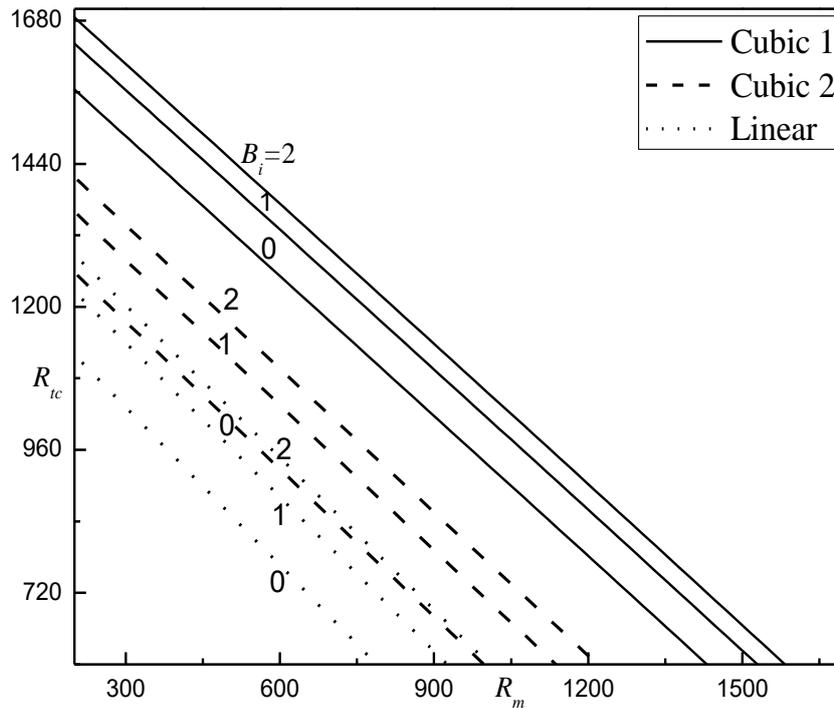


Figure. 3 Variation of R_{tc} vs R_m for different values of B_i when $M_3 = 1$.

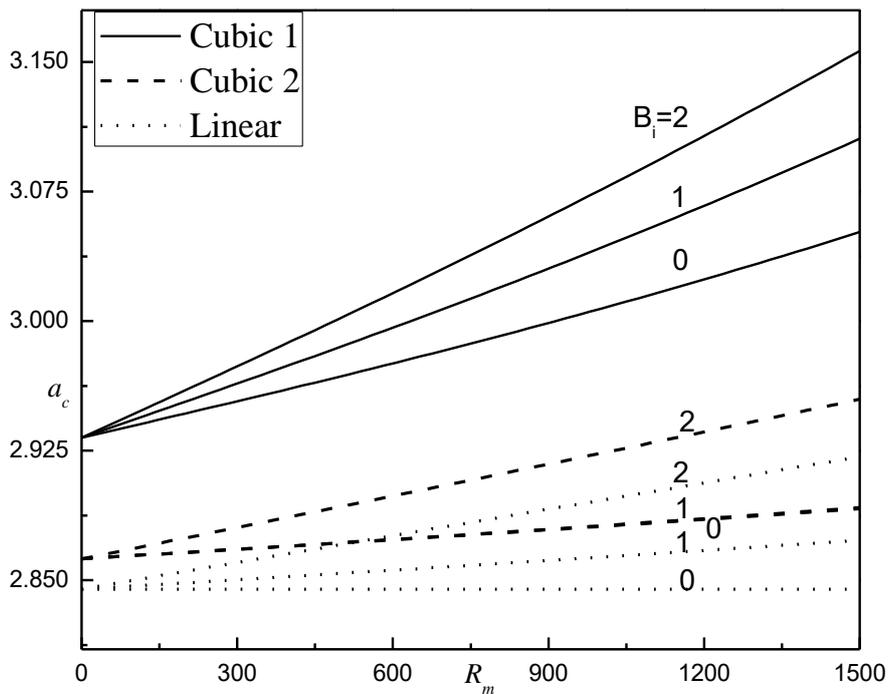


Figure. 4 Variation of a_c vs R_m for different values of B_i when $M_3 = 1$.

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