

A Bivariate Replacement Policy for an Extreme Shock Maintenance Model Under QUASI Renewal Process

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Abstract: Considering an extreme shock maintenance model for a degenerative simple repairable system, explicit expressions for the long-run average cost under the bivariate replacement policy (T, N) has been obtained. Existence of optimal value of (T, N) has been deduced.

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1. INTRODUCTION

Chen and Li (2008) have considered an extreme shock model and studied the maintenance problem under N policy. Considering the extreme shock model, we study the maintenance problem using the bivariate replacement policy. We also show that the bivariate optimal replacement policy $(T, N)^*$ is better than the univariate optimal replacement N^* and T^* policies.

The rest of the paper is organized as follows. In section 2, we present an extreme shock model for the maintenance problem of a repairable system. In section 3, explicit expressions for the long-run average cost under a bivariate replacement policy (T, N) is derived. Existence of the optimality under the bivariate replacement policy is deduced. Finally, conclusion is given in section 4.

2. MODEL DESCRIPTION

We make the following assumptions about the model for a simple degenerative repairable system subject to shocks.

- 2.1 At time $t = 0$, a new system is installed. Whenever the system fails, it will be repaired. The system will be replaced by an identical new one, some times later.
- 2.2 Once the system is operating, the shocks from the environment arrive according to a renewal process. Let $X_{ni}, i = 1, 2, \dots$ be the intervals between the $(i - 1)$ -st and i -th shock, after the $(n - 1)$ -st repair. Let $E(X_{11}) = \lambda$. Assume that $X_{ni}, i = 1, 2, \dots$, are *iid* sequences, for all $n \in N$.
- 2.3 Let $Y_{ni}, i = 1, 2, \dots$ be the sequence of the amount of shock damage produced by the i -th shock, after the $(n - 1)$ -st repair. Let $E(Y_{11}) = \mu$. Then $\{Y_{ni}, i = 1, 2, \dots\}$ are *iid* sequences, for all $n \in N$. If the system fails, it is closed, so that the random shocks have no effect on the system during the repair time. In the n -th operating stage, that is, after the $(n - 1)$ -st repair, the system will fail, if the amount of the shock damage first exceed

$a^{n-1}M$, where $0 < a \leq 1$ and M is a positive constant.

- 2.4 Let $Z_n, n = 1, 2, \dots$ be the repair time after the n -th repair and $Z_n, n = 1, 2, \dots$ constitute a non decreasing quasi renewal process with $E(Z_1) = \delta$ and ratio b , such that $0 < b < 1$. $N_n(t)$ is the counting process denoting the number of shocks after the $(n - 1)$ -st repair. It is clear that $E(Z_n) = \delta b^{n-1}$.
- 2.5 Let r be the reward rate per unit time of the system when it is operating and c be the repair cost rate per unit time of the system and the replacement cost is R . The replacement time is a random variable Z with $E(Z) = \tau$.
- 2.6 The sequences $\{X_{ni}, i = 1, 2, \dots\}$, $\{Y_{ni}, i = 1, 2, \dots\}$, $\{Z_n, n = 1, 2, \dots\}$ and Z are independent.
- 2.7 The replacement policy (T, N) is adapted.

3. THE BIVARIATE REPLACEMENT POLICY (T, N)

In this section, we study an extreme shock model for the maintenance problem of a simple repairable system under (T, N) policy. Let

$$L_n = \min\{l; Y_{nl} > a^{n-1}M\}$$

and $W_n = \sum_{i=1}^{L_n} X_{ni}$.

Thus, L_n is the number of shocks until the first deadly shock occurred following the $(n - 1)$ -st failure and L_n has a geometric distribution with $P\{L_n = k\} = p_n q_n^{k-1}$, $k = 1, 2, \dots$, where $p_n = P\{Y_{n1} > a^{n-1}M\}$ and $q_n = 1 - p_n$. We have $E(L_n) = \frac{1}{p_n}$. Since $\{X_{ni}, i = 1, 2, \dots\}$ and $\{Y_{ni}, i = 1, 2, \dots\}$ are independent, it is clear that L_n and $\{X_{ni}, i = 1, 2, \dots\}$ are independent. Now

$$\begin{aligned} E(W_n) &= E\left(\sum_{i=1}^{L_n} X_{ni}\right) \\ &= E(L_n)E(X_{n1}) \end{aligned}$$

$$= \frac{\lambda}{p_n}$$

The distribution function of W_n is $F_n(\cdot)$.

The working age T of the system at time t is the cumulative life-time given by

$$T(t) = \begin{cases} t - V_n, & U_n + V_n \leq t < U_{n+1} + V_n \\ U_{n+1}, & U_{n+1} + V_n \leq t < U_{n+1} + V_{n+1} \end{cases}$$

where $U_n = \sum_{i=1}^n W_i$ and $V_n = \sum_{i=1}^n Z_i$ and $U_0 = V_0 = 0$.

Let T_1 be the first replacement time; in general for $n = 2, 3, \dots$, let T_n be the time between the $(n - 1)$ -st replacement and the n -th replacement. Thus the sequence $\{T_n, n = 1, 2, \dots\}$ forms a renewal process. A cycle is completed, if a replacement is done. A cycle is actually the time interval between the installation of the system and the first replacement or the time interval between two consecutive replacements. Finally, the successive cycles together with the cost incurred in each cycle will constitute a renewal reward process. The length of the cycle under the replacement policy (T, N) is

$$W = \left(T + \sum_{n=1}^{\eta} Z_n \right) \chi_{(U_N > T)} + \left(\sum_{n=1}^N W_n + \sum_{n=1}^{N-1} Z_n \right) \chi_{(U_N \leq T)} + Z,$$

where $\eta = 0, 1, 2, \dots, N - 1$ is the number of failures before the working age of the system exceeds T and $\chi_{(A)}$ denotes the indicator function. The expected length of the cycle is

$$\begin{aligned} E(W) &= E \left[\left(T + \sum_{n=1}^{\eta} Z_n \right) \chi_{(U_N > T)} \right] \\ &\quad + E \left[\left(\sum_{n=1}^N W_n + \sum_{n=1}^{N-1} Z_n \right) \chi_{(U_N \leq T)} \right] \\ &\quad + E(Z) \\ &= E[T \chi_{(U_N > T)}] + E[(\sum_{n=1}^{\eta} Z_n) \chi_{(U_N > T)}] \\ &\quad + E\{E[(\sum_{n=1}^N W_n + \sum_{n=1}^{N-1} Z_n) \chi_{(U_N \leq T)} | U_N = u]\} + E(Z) \\ &= T \bar{F}_N(T) + \sum_{n=1}^{N-1} (\delta \beta^{n-1}) E[\chi_{(U_n \leq T < U_{n+1})}] \\ &\quad + \int_0^T E(\sum_{n=1}^N W_n) u dF_N(u) + \int_0^T (\sum_{n=1}^{N-1} E(Z_n)) dF_N(u) + \tau \end{aligned}$$

$$\begin{aligned} &= T \bar{F}_N(T) + \sum_{n=1}^{N-1} \delta \beta^{n-1} P(U_n \leq T < U_{n+1}) \\ &\quad + \sum_{n=1}^N \frac{\lambda}{p_n} \int_0^T u dF_N(u) + \sum_{n=1}^{N-1} (\delta \beta^{n-1}) F_N(T) + \tau \\ &= T \bar{F}_N(T) + \sum_{n=1}^{N-1} (\delta \beta^{n-1}) [F_n(T) - F_N(T)] \\ &\quad + \sum_{n=1}^N \frac{\lambda}{p_n} \int_0^T u dF_N(u) + \sum_{n=1}^{N-1} (\delta \beta^{n-1}) F_N(T) + \tau \\ &= T \bar{F}_N(T) + \delta \sum_{n=1}^{N-1} F_n(T) \beta^{n-1} + \sum_{n=1}^N \frac{\lambda}{p_n} \int_0^T u dF_N(u) + \tau \quad (3.1) \end{aligned}$$

Let $C(T, N)$ be the long-run average cost per unit time under the bivariate replacement policy (T, N) . By the renewal reward theorem, the long-run average cost per unit time under the replacement policy- (T, N) is given by

$$C(T, N) = \frac{\text{the expected cost incurred in a cycle}}{\text{the expected length of a cycle}}$$

$$= \frac{[E\{(c \sum_{n=1}^{\eta} Z_n - rT) \chi_{(U_N > T)}\} + c_p E(Z)] + [E\{(c \sum_{n=1}^{N-1} Z_n - r \sum_{n=1}^N W_n) \chi_{(U_N \leq T)}\} + R]}{E(W)} \quad (3.2)$$

Using the equation (3.1) in equation (3.2), we obtain the following result.

Theorem 3.1 For the model described in Section 2, under the assumptions 2.1 to 2.7, the long-run average cost per unit time under the bivariate replacement policy (T, N) for a simple degenerative repairable system is given by

$$C(T, N) = \frac{c \delta \sum_{n=1}^{N-1} F_n(T) \beta^{n-1} + c_p \tau + R - r T \bar{F}_N(T) - r \sum_{n=1}^N \frac{\lambda}{p_n} \int_0^T u dF_N(u)}{T \bar{F}_N(T) + \delta \sum_{n=1}^{N-1} F_n(T) \beta^{n-1} + \sum_{n=1}^N \frac{\lambda}{p_n} \int_0^T u dF_N(u) + \tau}$$

Deductions

The long-run average cost $C(T, N)$ is a bivariate function in T and N . Obviously, when N is fixed, $C(T, N)$ is a function of T . For fixed $N = m$, it can be written as

$$C(T, N) = C_m(T), \quad m = 1, 2, \dots$$

Thus, for a fixed m , we can find T_m^* by analytical or numerical methods such that $C_m(T_m^*)$ is minimized. That is, when $N = 1, 2, \dots, m, \dots$, we can find $T_1^*, T_2^*, T_3^*, \dots, T_m^*, \dots$, respectively, such that the corresponding $C_1(T_1^*), C_2(T_2^*), \dots, C_m(T_m^*), \dots$ are minimized. Because the total life-time of a multistate

degenerative system is limited, the minimum of the long-run average cost per unit time exists. So we can determine the minimum of the long-run average cost per unit time based on $C_1(T_1^*), C_2(T_2^*), \dots, C_m(T_m^*), \dots$.

Then, if the minimum is denoted by $C_n(T_n^*)$, we obtain the bivariate optimal replacement policy $(T, N)^*$ such that

$$\begin{aligned} C((T, N)^*) &= \min_N C_n(T_n^*) \\ &= \min_N [\min_T C(T, N)] \\ &\leq \min_N C(\infty, N) \equiv C(N^*) \end{aligned}$$

the optimal policy $(T, N)^*$ is better than the optimal policy N^* . Moreover, under some mild conditions, Stadje and Zuckerman (1990) showed that an optimal replacement policy N^* is better than the optimal policy T^* . So under the same conditions, an optimal policy $(T, N)^*$ is better than the optimal replacement policies N^* and T^* .

4. CONCLUSION

Considering an extreme shock maintenance model for a degenerative simple repairable system, explicit expressions for the long-run average cost under the bivariate replacement policy (T, N) has been obtained. Existence of optimal value of (T, N) has been deduced.

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