Performance Analysis of Acquisition Algorithms for NavIC

N.Alivelu Manga

Abstract—Indian Regional Navigation Satellite System (IRNSS), is an indigenous navigation system designed and developed by ISRO(Indian Space Research Organization). It is named as NavIC, Navigation with Indian Constellation by Indian Prime Minister. NavIC is designed to have seven satellite constellation that provides reliable position, navigation and timing services over India. The focal modules of NavIC receiver are acquisition, tracking and navigation unit. Amongthem, acquisition is the data processing unit for detecting satellite signals and their corresponding code phase and carrier frequency. In this paper, various acquisition algorithms like Serial search and Parallel Code Phase search algorithms are analyzed and compared with Cooley-Tukey FFT algorithm and sub-sampled Fast Fourier transform (ssFFT). The results obtained in MATLAB shows that theacquisition computation time for ssFFT based NavIC receiver is faster than parallel FFT acquisition and the Cooley-Tukey FFT IRNSS acquisition algorithm is faster and provides better code phase and carrier frequency values compared to serial search acquisition algorithm.

IndexTerms— IRNSS, NavIC, acquisition, parallel code phase search algorithm, serial search acquisition algorithm, ssFFT, Cooley-Tukey FFT.

I. INTRODUCTION

Indian Regional Navigation Satellite System provides position, velocity and time over Indian region(JitenderSingh et al., 2012) It is developed ISRO and coined as NavIC by Prime Minister of India. The IRNSS project was approved by government of India in June 2006 with a sanction of 1420 Cr (Bhaskaranarayana, A, 2008). The IRNSS constellation consists of 7 satellites of which, three are in GEO stationary and four are in GSO synchronous orbits. The IRNSS provide two services namely Standard Position Service (SPS) and Restricted Service (RS). The main modules of NavIC receiver are acquisition, tracking and navigation unit. Among them, acquisition is the data processing unit for detecting satellite signals and their corresponding code phase and carrier frequency. This paper is planned into six sections. SPS signal generation is discussed in Section II. Section III describes the receiver architecture. Section IV describes the signal conventional acquisition algorithms and ssFFT and

Manuscript revised May 13, 2019 and published on June 5, 2019 N.Alivelu Manga, Associate Professor, Department of ECE, Chaitanya Bharathi Institute of Technology, Hyderabad, Telangana, India Cooley-Tukey acquisition algorithms. Section V shows the simulation results of the explained acquisition algorithms and their performance comparisons and conclusions are presented in Section VI.

II. SPS SIGNAL GENERATION

In the process of generation of L5 signal, P-code and navigation data are together multiplied. The next step is the application of BPSK (Binary Phase Shift Keying) modulation with the incoming carrier signal. After that, C/A (Coarse/Acquisition) code is multiplied with navigation data, then application of BPSK modulation with 90degrees phase shifted version of incoming carrier signal. Obtained results from the two modulators are added get L5 signal of frequency 1175.45MHz (Fig. 1). To generate L5 signal of frequency 1176.45MHz, a common frequency signal of frequency, f_0 =10.23MHz is used



Fig. 1SPS signal generator Block diagram

The modulo-2 (\bigoplus) addition gives a signal with values $\{1,0\}$ which is then BPSK modulated with carrier signal to obtain a L5 signal with values $\{-1,1\}$. The chipping rate for C/A code is considered as 1.023 MHz and navigation data bit rate is 50 Hz(Anil Manandhar,2017).

A unique C/A code is utilized by each of the satellite for the implementation of CDMA. The C/A codes are generated using pseudorandom noise (PRN) codes, also known as Gold codes. Two Linear Feedback Shift Registers (LFSR), G1 and G2 each of 10 bits, generate maximum length PRN codes having a length of $2^{10} - 1$ bits. The length of each generated code is 1023 chips. The code chipping rate used is 1.023 Mcps. The polynomials G1 and G2 used for SPS code generation are defined as given below:

$$G1 (X) = 1 + X^3 + X^{10}$$
$$G2 (X) = 1 + X^2 + X^3 + X^6 + X^8 + X^9 + X^{10}$$

International Journal of Research in Advent Technology, Vol.7, No.6S, June 2019 E-ISSN: 2321-9637 Available online at www.ijrat.org

These polynomials are analogous to the ones used for GPS C/A signal. These polynomials are implemented by using Maximum Length Feedback Shift Registers (MLFSR) each of length 10 bits. The initial state of G2 register provides the chip delay. The all bits of the G1 register are initialized to 1. Then, the bits of these two registers are exclusive-OR'ed to obtain the final PRN sequence of length 1023 chips. For all 7 satellites, the time period of the PRN sequence is 1 millisecond

III. IRNSS RECEIVER ARCHITECTURE

IRNSS receiver is a system where the Signal In Space (SIS) is processed to determine user's position velocity and time. The functions of various sections of IRNSS receiver (Fig.2) in brief are:

- a) Antenna and preamplifier: Detects the electromagnetic waves arriving from the satellite, converts the wave energy into an electrical current, amplifies the signal strength and passes on the signal receiver electronics. Voltage induced by IRNSS signal in the antenna is sent to the preamplifier.
- b) RF/IF Section : The RF signal is mixed with a locally generated sinusoidal signal to down convert IRNSSsignal to a lower frequency IF signal. This IF signal contains all code and data signals from the original RF signal with low carrier frequency.
- c) **Acquisition :** The process of Acquisition detects satellite signal coming from a given IRNSS satellite and provides coarse values of the code phase and the carrier frequency.
- d) **Tracking:**It refines the values produced by acquisition and tracks their changes continuously. It mainly consists of code tracking and carrier tracking loops.
- e) **NAV unit**: Therole of an NAV unit block is to compute the IRNSS basic measurements: pseudo range, carrier phase and Doppler shift (or its pseudo range rate version).



Fig.2 IRNSS Receiver Architecture

IV. ACQUISITON ALGORITHMS

From the acquisition process, satellite signal is detected and its corresponding coarse values of codephase and carrier frequency are estimated. There are several algorithms for acquisition GNSS/IRNSS signals including Serial search or time domain acquisition algorithm, Parallel code phase search or FFT based algorithm, Parallel frequency code phase search acquisition.

A. Serial Search Acquisition Algorithm

Serial search acquisition is a simple and is a time domain acquisition algorithm(Fredrik Johanssonet al., 1998). The process of serial search acquisition is shown in Fig.3. In thislocally generated PRN code sequences are multiplied with locally generated replica of the carrier signal. Initially, the received IRNSS signal is multiplied with locally generated PRN sequence. Then, the result is multiplied by a local carrier signal to wipe off the carrier signal from the incoming signal. A in-phase signal I is generated bv multiplication with in phase carrier signal replica, and multiplication with 90 degrees phase-shifted carrier signal replica, the quadrature signal Q is generated. The resulted I and Q signals are combined. This is done based on the length of one PRN code, and are squared and added finally. Code phase value is inferred from the serial search acquisition which gives the correlation between the locally generated signal with that of the incoming signal.



Fig.3 Serial Acquisition

B. Parallel Code Phase Search Acquisition Algorithm

Parallel Code Phase Search Acquisition Algorithm is Fast Transform based acquisition algorithm and Fourier Frequency domain type. In this particular technique, acquisition is done parallel in a code phase dimension to speed up the acquisition process significantly. The received IF signal and the local carrier signal are multiplied together. The I (in-phase) signal is generated by multiplication with in phase signal and Q (quadrature) signal is generated by multiplication with a quad phase-shifted version of the signal. The I and Q signals are grouped to result in a complexinput to the FFT function. The PRN code, generated for a specific satellite is changed into the frequency domain and complex conjugated. Then, the IF signal and PRN code are multiplied together in the frequency domain. The result is then changed into the time domain by applying an inverse Fourier transform (Fig 4). Then, the correlation between the input and the PRN code represented by the absolute value of this inverse Fourier transform. The index of the peak presented in the output of correlation, indicates the PRN code phase of the incoming signal.



Fig. 4 Parallel Code Phase Search Acquisition

C. SubSampled Fast Fourier Transform Acquisition

In this, the signal is down sampled by a factor 'd ', a decimator which is an integer (M.VenuGopalaRao et al.,2015). The IFFT shown in Fig.5 is sparse in the time domain, i.e., there will be only one spike in time domain. Hence, it can be performed in sub-linear time and alsorequire less number of samples as inputto compute the sparse IFFT. As a result, there is no need to perform a full-length computation the received signal and one can get all of itsfrequency samples. Here, the number of frequency samples that are required to perform the sparse inverse FFT need to be computed



Fig.5 Acquisition using sub sampled Fast Fourier Transform

D. FFT Acquisition Algorithm using Cooley Tukey FFT

A shown in Fig.6, the principle of Cooley-Tukey algorithm applied to compute N point DFT by decomposing into smaller size DFTs, which results in reduction of time of FFT computation.



Fig.6 Block diagram of Acquisition based on Cooley Tukey FFT Algorithm

V. RESULTS AND DISCUSSION

IRNSS SPS signal is generated for L5 signal and C/A code for different satellites (L5 band) are simulated in MATLAB.The various acquisition algorithms like serial search and parallel code phase search, to find code phase and carrier frequency of received IRNSS signals are simulated in sampling frequency used is 56 MATLAB. For this, the MHz, and carrier frequency is 16.221MHz. Apart from these algorithms, Sub Sampled Fast Fourier Transform Acquisition and FFT Acquisition Algorithm using Cooley Tukey FFT are also analyzed. IRNSS SPS signal for 0.05 milliseconds is shown Fig. 7. In Fig. 8,9,10,11,12,13 and 14x- axis indicates codephase, y- axis indicates frequency bin and z- axis indicates magnitude. Doppler shift is calculated using (frequency bin*125-5000). The acquisition results for satellite 4 using serial search method is with Doppler shift 500Hz and Code phase 23290 shown in Fig. 8. For satellite 4,the acquisition results using Parallel Code phase search method are presented in Fig 9 with Doppler shift 250Hz and Code phase is 853 for downsampled 8184 samples and for 56000*2 samples Code phase calculated is 23857.Fig 10,11,12 and 13shows Acquisition results for satellite 4 for downsample factor 2,3,4 and 6 respectively. In Fig. 10, Doppler shift is 250 Hz and Code phase is 426.In Fig. 11, Doppler shift 250 Hz and Code phase is 284. In Fig. 12 Doppler shift is 250Hz and Code phase is 213. In Fig. 13, Doppler shift is 250 Hz and Code phase is 142.Using Cooley Tukey FFT,8184 samples are divided into 88 and 93 samples. Fig. 14 shows Acquisition results for satellite 4 using Cooley Tukey FFT with Doppler shift is 250 Hz and code phase is 853. The Table 1 shows the acquisition results for available data using serial search method. The acquisition results using Parallel Code Phase Search Acquisition Algorithm are given in the Table 2. Acquisition results of satellite 4 using sub sampled FFT are presented in Table 3. Table 4 shows Acquisition results using Cooley Tukey FFT method. Table 5 shows Comparison of acquisition results for satellite 4 using different acquisition algorithms.



International Journal of Research in Advent Technology, Vol.7, No.6S, June 2019 E-ISSN: 2321-9637 Available online at www.ijrat.org



Fig.7 SPS generation for 0.05 milliseconds



Fig.8 Acquisition results for satellite 4 using serial search method

Fig.9 Acquisition results for satellite 4 using parallel code phase method



Fig.10 Acquisition results of satellite 4 for down sample factor 2

Fig.11 Acquisition results of satellite 4 for down sample factor 3





Fig.12 Acquisition results of satellite 4for down sample factor 4

Fig 13 Acquisition results of satellite 4for down sample factor 6



Fig.14 Acquisition results for satellite 4 using Cooley Tukey FFT

Table 1: Acquisition results for different satellites	using				
sarial saarch mathod					

serial search method				
S.No.	L5-SPS G2	Code phase	Doppler shift(Hz)	Carrier frequency (Hz)
1	1110010111	55220	-1500	16219500
2	0110010000	30766	+250	16221500
3	0010110001	54927	-125	16221500
4	0100111010	23290	+250	16221500
5	0000110111	39820	-125	16221500
6	1101011000	2270	-125	16221500
7	0010100000	29315	+375	16221500

Table 2: Acquisition results for different satellites using Parallel Code Phase Search Acquisition Algorithm

S.N 0.	L5-SP S G2	Code phase in 8184 samples	Code phase in 56000*2 samples	Doppl er shift(Hz)
1	11100 10111	2020	56533	-2125
2	01100 10000	1126	31501	+250

International Journal of Research in Advent Technology, Vol.7, No.6S, June 2019 E-ISSN: 2321-9637 Available online at www.ijrat.org

3	00101 10001	2009	56225	-125
4	01001 11010	853	23857	+250
5	00001 10111	1457	40769	-250
6	11010 11000	85	2353	-125
7	00101 00000	1073	30017	-125

 Table 3: Acquisition Results of satellite 4 using sub sampled FFT

S N 0	d	Code phase	Carri er freque ncy(H z)	time (sec)	d*lo g(d)
1	-	853	16221 250	17.10 07	
2	2	426*2+1 =853	16221 250	16.45 22	2
3	3	284*3+1 =853	16221 250	16.35 71	4.75
4	4	213*4+1 =853	16221 250	16.29 46	8
5	6	142*6+1 =853	16221 250	15.87 8274	15.5 1

 Table 4: Acquisition results for different satellites using

 Cooley Tukey FFT method

S N o.	L5-SPS G2	Code phase in 8184 samples	Code phase in 56000*2 samples	Dopple r shift(H z)
1	1110010 111	2020	56533	-2125
2	0110010 000	1126	31501	+250
3	0010110 001	2009	56225	-125
4	0100111 010	853	23857	+250
5	0000110 111	1457	40769	-250
6	1101011 000	85	2353	-125
7	0010100 000	1073	30017	-125

 Table 5: Comparison of acquisition results for satellite 4

 using different acquisition algorithms

Acquisition Algorithm	Code phase	Carrier frequency(MHz)	Time (sec)
Serial search	23290	16.221500	1079.7422
Parallel Code			
Phase Search	23857	16.221250	17.7001
Acquisition			

Algorithm			
FFT Acquisition Algorithm using Cooley Tukey FFT	23857	16.221250	119.01

VI. CONCLUSION

In this paper, various acquisition algorithms forNavIC signals are simulated and analyzed. It is observed that, Parallel FFT(17.7001 s) is faster than Serial Search acquisition algorithm(1079.7422 s).Reduction in the acquisition time and computation complexity is observed by the exploitation of properties of sparse FFT, Fourier transform and decimator and by the use of sub sampled FFT. From the simulation, it is observed that the acquisition time is decreased from (17.7001 s) to (15.878274 s) for downsampling factor 6 without change in the code phase and Doppler frequency shift.The Cooley-Tukey algorithm is also analyzed, it is noticed that, in comparison with Serial search Acquisition algorithm (1079.7422 s), Parallel Code Phase Search (17.7001 s) and Cooley Tukey FFT (119.01 s) Acquisition algorithm is faster.

REFERENCES

- (Hofmann-Wellenhof, B., Lichtenegger, H., and Collins, J., "Global Positioning System: Theory and Practice," 5th edition, Springer-Verlog, Berlin Heidelberg New York, 389 pp. 2001.
- [2] Parkinson, B.W., "Global Positioning System: Theory and Applications", Vol. I, AIAA Publication, 1996
- [3] JitenderSingh,Sc'D' and J. Rammohan, Sc'G'"Indian Regional Navigation Satellite System and its Defence Applications", NAVCOM-2012 December, Hyderabad.
- Bhaskaranarayana, A. (July 15th 2008) Indian IRNSS &GAGAN, Presentation to COSPAR Meeting, Montreal.
- [5] Kaplan, E.D., "Understanding GPS: Principle and Applications," 2nd Edition, Artech HousePublishers, 2005
- [6] Misra. P and Enge. P., "Global Positioning System: Signals, Measurements, and Performance," Ganga-Jamuna Press, 2001
- [7] S. Naveen Pitchumani, S. ArunSundar, T. Srinivasan, and S. Savithri," Mathematical Modelling of Indian Regional Navigation Satellite System Receiver", Defence Science Journal, Vol. 67, No. 4, July 2017
- [8] PoojaV.Thakar, HirenMewada "Receiver Acquisition Algorithms and their Comparisons for BOC modulated Satellite Navigation Signal", 2012 International Conference on Communication Systems and Network Technologies.
- [9] M.VenuGopalaRaoand D. VenkataRatnam," Faster Acquisition Technique for Software-defined GPS Receivers", Defence Science Journal, Vol. 65, No. 1, January 2015
- [10] D.VenkataRatnam, Ashish Pasha, Swathi P, M.VenuGopalaRao," Acquisition of GPS L1 Signals Using Cooley-Tukey FFT Algorithm", SignalProcessing, Computing and Control(ISPCC),2013 IEEE Conference.
- [11] IRNSS Signal In Space ICD for standard positioning service version 1.1, August 2017 (http://www.isro.gov.in/irnss-programme).
- [12] Anil Manandhar "FPGA-based Tracking System for GNSS Receivers", June 6, 2017.
- [13] Fredrik Johansson, RahmanMollaei, Jonas Thor, Jorgen Uusitalo, "GPS Satellite Signal Acquisition and Tracking" August 21,1998
- [14] RishijaMisra and ShubhamPalod, "Code and Carrier Tracking Loops for GPS C/A Code", International Journal of Pure and Applied Sciences and Technology, 2011
- [15] James Bao-Yen Tsui "Fundamentals of Global Positioning System Receivers: A Software Approach" Copyright 2000 John Wiley & Sons, Inc